THE STRAIN RATE TENSOR

In this lesson, we will:

- Define **linear strain rate**, **volumetric strain rate**, and **shear strain rate**
- Discuss how to combine the linear and shear strain rates into the **strain rate tensor**
- Do some example problems

Linear Strain Rate

Example: Linear Strain Rate

Given: A steady, 2-D velocity field is given by components

$$
u = 2xy
$$

$$
v = -y^2
$$

$$
w = 0
$$

To do: Calculate the three linear strain rates.

Solution:
$$
\varepsilon_{xx} = \frac{\partial u}{\partial x}, \varepsilon_{yy} = \frac{\partial v}{\partial y}, \varepsilon_{zz} = \frac{\partial w}{\partial z}
$$

 $\left\{\begin{array}{ccc} \mathcal{E}_{xx} = 2y & \mathcal{E}_{yy} = -2y & \mathcal{E}_{zz} = 0 \end{array}\right\}$

Shear Strain Rate

Shear strain is defined as half of the decrease of the angle between two initially perpendicular lines that intersect at a point.

The Strain Rate Tensor $2^{n\delta}$ order tensor $(9$ -components). Write as a 3x3 matrix · Scalar -> magnitude only (ath-order tenjor) Vector - magnitude à direction (1st orde tever) - znd order tempor - magnitude i. direction, depending on surface orientation $\overrightarrow{\mathcal{E}} = \mathbf{\mathcal{E}} = \overrightarrow{\mathcal{E}}_{ij} = \begin{pmatrix} \varepsilon_{11} & \varepsilon_{12} & \varepsilon_{13} \\ \varepsilon_{21} & \varepsilon_{22} & \varepsilon_{23} \\ \varepsilon_{31} & \varepsilon_{32} & \varepsilon_{33} \end{pmatrix} = \begin{pmatrix} \varepsilon_{xx} & \varepsilon_{xy} & \varepsilon_{yz} \\ \varepsilon_{yx} & \varepsilon_{yy} & \varepsilon_{yz} \\ \varepsilon_{zx} & \varepsilon_{zy} & \varepsilon_{zz} \end{pmatrix}$ $1 - 7$ Eij will be important later when we derive the differential $\label{eq:11} \varepsilon_{ij}=\begin{pmatrix} \varepsilon_{xx} & \varepsilon_{xy} & \varepsilon_{xz} \\ \varepsilon_{yx} & \varepsilon_{yy} & \varepsilon_{yz} \\ \varepsilon_{zx} & \varepsilon_{zy} & \varepsilon_{zz} \end{pmatrix}=\frac{\frac{\partial u}{\partial x}}{\frac{1}{2}\left(\frac{\partial v}{\partial x}+\frac{\partial u}{\partial y}\right)}\underbrace{\left(\frac{1}{2}\left(\frac{\partial u}{\partial y}+\frac{\partial v}{\partial x}\right)\right)}_{\frac{\partial v}{\partial y}}\underbrace{\left(\frac{1}{2}\left(\frac{\partial u}{\partial z}+\frac{\partial w}{\partial x$ g components 6 independent componenty

Example: Rates of motion and deformation (Continuation of previous example) Given: A two-dimensional velocity field in the *x*-*y* plane: $|\vec{V} = (u,v) = 3x\vec{i} - 3y\vec{j}|(w = 0)$. **To do**: Calculate (**a**) rate of translation, (**b**) rate of rotation, (**c**) the three linear strain rates, (**d**) the six shear strain rates, and (**e**) the strain rate tensor. **Solution**: We did Parts (**a**) and (**b**) in a previous lesson for this velocity field. Recall, \vec{r} \vec{r} \vec{r} (a) The rate of translation is simply the velocity vector, $V = u\vec{i} + v\vec{j} + wk$. Here, the rate of translation = $|\vec{V} = 3x\vec{i} - 3y\vec{j}|$. $\vec{v} = \frac{1}{2} \left(\frac{\partial w}{\partial x} - \frac{\partial v}{\partial y} \right) \vec{i} + \frac{1}{2} \left(\frac{\partial u}{\partial y} - \frac{\partial w}{\partial x} \right) \vec{j} + \frac{1}{2} \left(\frac{\partial v}{\partial y} - \frac{\partial u}{\partial x} \right) \vec{k}$. Here, $\vec{\omega} = \frac{1}{2} \left(\frac{\partial w}{\partial y} - \frac{\partial v}{\partial z} \right) \vec{i} + \frac{1}{2} \left(\frac{\partial u}{\partial z} - \frac{\partial w}{\partial x} \right) \vec{j} + \frac{1}{2} \left(\frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right)$ **(b)** The rate of rotation is $\vec{\omega} = \frac{1}{2} \left(\frac{\partial w}{\partial x} - \frac{\partial v}{\partial y} \right) \vec{i} + \frac{1}{2} \left(\frac{\partial u}{\partial x} - \frac{\partial w}{\partial y} \right) \vec{j} + \frac{1}{2}$ $\left[\frac{w}{i} - \frac{\partial v}{\partial x}\right]\vec{i} + \frac{1}{2}\left[\frac{\partial u}{\partial x} - \frac{\partial w}{\partial y}\right]\vec{j} + \frac{1}{2}\left[\frac{\partial v}{\partial x} - \frac{\partial u}{\partial y}\right]\vec{k}$ $=\frac{1}{2}\left[\frac{\partial w}{\partial y}-\frac{\partial v}{\partial z}\right]\vec{i}+\frac{1}{2}\left[\frac{\partial u}{\partial z}-\frac{\partial w}{\partial x}\right]\vec{j}+\frac{1}{2}\left[\frac{\partial v}{\partial x}-\frac{\partial u}{\partial y}\right]$ $2(\partial y \partial z)$ $2(\partial z \partial x)^{3}$ 2 the rate of rotation is $\vec{\omega} = 0$, and the vorticity = $\vec{\zeta} = 2\vec{\omega} = 0$. This flow is *irrotational*. (**c**) The three components of linear strain rate are $U = 3x - 12 - 34$ $=\frac{\partial u}{\partial x}, \ \ \varepsilon_{yy}=\frac{\partial v}{\partial y}, \ \ \varepsilon_{zz}=\frac{\partial w}{\partial z}$ $\epsilon_{xx} = \frac{\partial u}{\partial x}, \quad \epsilon_{yy} = \frac{\partial v}{\partial y}, \quad \epsilon_{zz} = \frac{\partial w}{\partial z}$ $\varepsilon_{xx} = \frac{\partial}{\partial x}, \quad \varepsilon_{yy} = \frac{\partial}{\partial y}, \quad \varepsilon_{zz} = \frac{\partial}{\partial z}$ $\mathcal{A} \text{ None: } \mathcal{E}_{xx} + \mathcal{E}_{yy} + \mathcal{E}_{zz} = 0$ (**d**) The three components of shear strain rate are $\varepsilon_{-} = \varepsilon_{-} = \frac{1}{\alpha} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)$, $\varepsilon_{-} = \varepsilon_{-} = \frac{1}{\alpha} \left(\frac{\partial w}{\partial y} + \frac{\partial u}{\partial z} \right)$, $\varepsilon_{-} = \varepsilon_{-} = \frac{1}{\alpha} \left(\frac{\partial v}{\partial y} + \frac{\partial w}{\partial w} \right)$ $\epsilon_{xx} = \mathcal{E}_{yx} = \frac{1}{2} \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right), \ \ \ \lambda_{xx} = \mathcal{E}_{xz} = \frac{1}{2} \left(\frac{\partial w}{\partial x} + \frac{\partial u}{\partial z} \right), \ \ \ \lambda_{yx} = \mathcal{E}_{xy} = \frac{1}{2} \left(\frac{\partial v}{\partial z} + \frac{\partial w}{\partial y} \right).$ $=\varepsilon_{yx}=\frac{1}{2}\left(\frac{\partial u}{\partial y}+\frac{\partial v}{\partial x}\right),\quad\bigg\vert \varepsilon_{zx}=\varepsilon_{xz}=\frac{1}{2}\left(\frac{\partial w}{\partial x}+\frac{\partial u}{\partial z}\right),\quad\bigg\vert \varepsilon_{yz}=\varepsilon_{zy}=\frac{1}{2}\left(\frac{\partial v}{\partial z}+\frac{\partial w}{\partial y}\right)$ $=\frac{1}{2}(0+0)$ = Ω Ξ0 $(\iota\mathcal{D})$ $(2-0)$ In this flow, there is no shear strain & (**e**) The strain rate tensor $= \begin{pmatrix} {\cal E}_{xx} & {\cal E}_{xy} & {\cal E}_{xz} \ {\cal E}_{yx} & {\cal E}_{yy} & {\cal E}_{yz} \ {\cal E}_{zx} & {\cal E}_{zy} & {\cal E}_{zz} \end{pmatrix}$ εεε *xx* \boldsymbol{c}_{xy} \boldsymbol{c}_{xz} \overline{O} $\varepsilon_{\nu} = \varepsilon_{\nu} \varepsilon_{\nu} \varepsilon_{\nu} \varepsilon_{\nu}$ *ij* $\boldsymbol{\epsilon}$ $\boldsymbol{\epsilon}$ $\boldsymbol{\mu}$ $\boldsymbol{\epsilon}$ $\boldsymbol{\nu}$ $\boldsymbol{\nu}$ $\boldsymbol{\nu}$ $\boldsymbol{\epsilon}$ $\boldsymbol{\nu}$ *zx zy zz* Here, the x-y axes are principal axes & If we retate axes, all of these components will change

Volumetric Strain Rate

Volumetric strain is defined as the change of volume of a fluid particle per unit volume following a fluid particle.

