## **Comprehensive Equation Sheet for M E 320**

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Notation for this equation sheet: V = volume, V = velocity, v = y-component of velocity, v = kinematic viscosity

• Constants: 
$$\left[g = 9.807\frac{m}{s^2}\right]P_{m} = 101.3 \text{ kPa}$$
  $\rho_{m} = 1204\frac{kg}{m^2}\right]\rho_{mm} = 998.0\frac{kg}{m^2}\rho_{mmon} = 13.600\frac{kg}{m^2}$   
• Conversions:  $\left[\frac{N+s^2}{kg}\right]\left[\frac{Pa+m^2}{N}\right]$   $\left[\frac{kW-s}{1000 \text{ N}\cdot m}\right]\left[\frac{(2\pi \text{ rad})}{1000 \text{ L}}\right]\left[\frac{(2\pi \text{ rad})}{(\pi \text{ tadion})}\right]T(\mathbf{K}) = T(^{\circ}\mathbf{C}) + 273.15$   
• Specific gravity:  $\overline{SG} = \rho/\rho_{(0)}$  I deal gas:  $\overline{P} = \rho RT \left[R = c_p - c_1\right] \left[k = c_p/c_1\right] \left[k_m = 1.40\right] \left[R_m = 300\frac{m^2}{s^2 \cdot \mathbf{K}}\right]$   
• Simple shear flow and viscosity:  $\overline{u(y) = Py/k}$  for flow sandwiched between two infinite flat plates:  $\left[\frac{r - \mu du}{dy}\right]$   
• Surface tension:  $\left[\frac{M_{boxe}}{2} - P_{mak} - P_{mak} - 2\frac{\sigma}{2}\right] \left[M_{boxe}^{1} - P_{amake} - P_{amake} - P_{amake} - 4\frac{\sigma}{R}\right]$  Capillary tube:  $\left[k = \frac{2\sigma}{Dg}\right]$   
• Gage, vacuum, and vapor pressure:  $\left[\frac{\mu_{uv}}{2m} - P_{amake} - P_{um}\left[\frac{Nm}{2m} - P_{amake}\right] P_{boxe}^{2} + 20 \text{ kPa for water at } T = 20^{\circ}\text{C}$   
• Hydrostatics:  $\left[\overline{\nabla P} - \rho g\right] \left[\frac{dt}{dt} - -\rho g\right] \left[\frac{R_{anw}}{P_{amax}} - P_{amake} - P_{amake}\right] \left[\frac{NP - \rho gh}{R}\right]$   
• Forces on submerged, plane surfaces (see sketch):  
 $\left[\frac{F = (P_a + \rho gk_a) (A = P_a A = P_{max}]}{p_a - s_a r_a + \frac{1}{(y_c + P_a^2)}(\rho g \sin \theta)}\right]A$   
Rectangle *a* wide and *b* talt:  $\left[\frac{I_{axc}}{2m} - \frac{d\overline{R}}{20}\right]$  Use modified gravity vector  
*G* in place of *g* everywhere.  
• Rigid body rotation (vertical axis, cylinder radius *R*):  
 $\left[\frac{z_{unace}}{h_a} - \frac{\sigma^2}{4g}\left(\frac{R^2}{2} - 2r\right\right]\left[P = P_a + \frac{D^2}{2}r^2 - \rho gg\right]$   
• Acceleration field and material derivative  $\left[\frac{d(x, y, z, t) - D\overline{P}_{b} - \overline{\partial t}^{2} + u \frac{\partial t}{\partial x} + v \frac{\partial t}{\partial y} + w \frac{\partial t}{\partial x}\right] \left[\frac{D}{D_{b}} - \frac{\partial b}{\partial a} + (\overline{V} \cdot \overline{b})b$   
• Vorticity vector:  $\left[\frac{\zeta}{z} = \nabla x I^{2} - \operatorname{cull}\left[\frac{D}{2} - \frac{\partial w}{2}\right] \overline{I} + \left(\frac{\partial w}{\partial x} - \frac{\partial w}{\partial x}\right] \overline{I} + \left(\frac{\partial w}{\partial x} - \frac{\partial w}{\partial x}\right] \overline{I} + \left(\frac{\partial w}{\partial x} - \frac{\partial w}{\partial x}\right] \left[\frac{R_{amax}}{R_{amax}} = \frac{u}{w}$  where in Cantesian coordinates,  $\left|\frac{V = m}{R} + \frac{\partial w}{Q} - \frac{\partial w}{Q_{am}}\right]$   
• Volumetric strain rate in Cartesian coordinates:  $\left[\frac{V = m}{V} + \frac{M}{M} - \frac{w$ 

Strain rate tensor in Cartesian coordinates:  

$$\varepsilon_{ij} = \begin{pmatrix} \varepsilon_{xx} & \varepsilon_{xy} & \varepsilon_{xz} \\ \varepsilon_{yx} & \varepsilon_{yy} & \varepsilon_{yz} \\ \varepsilon_{zx} & \varepsilon_{zy} & \varepsilon_{zz} \end{pmatrix} = \begin{pmatrix} \frac{\partial u}{\partial x} & \frac{1}{2} \left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) & \frac{1}{2} \left( \frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} \right) \\ \frac{1}{2} \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial z} \right) & \frac{\partial v}{\partial y} & \frac{1}{2} \left( \frac{\partial v}{\partial z} + \frac{\partial w}{\partial y} \right) \\ \frac{1}{2} \left( \frac{\partial w}{\partial x} + \frac{\partial u}{\partial z} \right) & \frac{1}{2} \left( \frac{\partial w}{\partial y} + \frac{\partial v}{\partial z} \right) & \frac{\partial w}{\partial z} \end{pmatrix}$$

**Reynolds transport theorem (RTT)**: For a fixed or non-fixed control volume, where B = some flow property, and b = B/m,

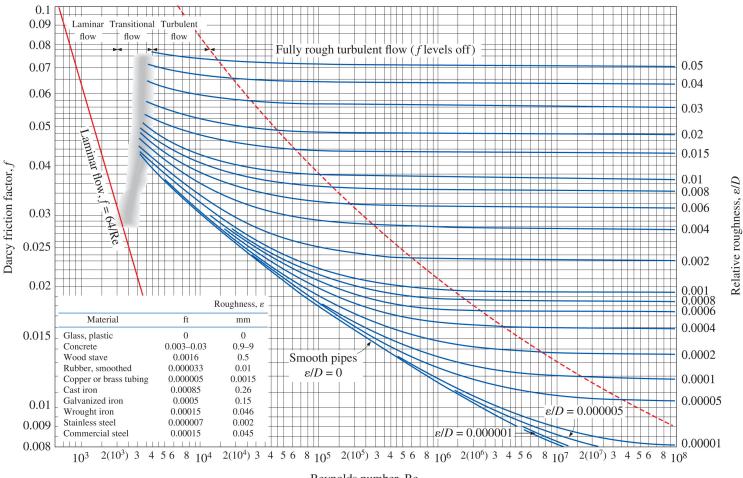
 $\frac{dB_{sys}}{dt} = \frac{d}{dt} \int_{CV} \rho b dV + \int_{CS} \rho b \vec{V}_r \cdot \vec{n} dA$  where  $\vec{V}_r = \vec{V} - \vec{V}_{CS}$  is the relative velocity **Conservation of mass for a CV**:  $\frac{dm_{\rm CV}}{dt} = \sum_{\rm in} \dot{m} - \sum_{\rm out} \dot{m} \left[ \dot{m} = \rho \dot{V} = \rho V_{\rm avg} A_c \right]$ at an inlet or outlet, where  $V_{\rm avg} = \frac{1}{A_c} \int V_{\rm normal} dA_c$ For *steady-state*, *steady flow* (*SSSF*) problems:  $\sum_{in} \dot{m} = \sum_{out} \dot{m}$ . For *incompressible SSSF*:  $\sum_{in} \dot{V} = \sum_{out} \dot{V}$ Conservation of energy for a CV:  $\dot{Q}_{\text{net in}} + \dot{W}_{\text{shaft, net in}} = \frac{d}{dt} \int_{\text{CV}} e\rho dV + \sum_{\text{out}} \dot{m} \left( h + \alpha \frac{V^2}{2} + gz \right) - \sum_{\text{in}} \dot{m} \left( h + \alpha \frac{V^2}{2} + gz \right)$ • where  $e = u + \frac{V^2}{2} + gz$   $h = u + \frac{P}{\rho}$   $\dot{m} = \rho V_{avg} A_c$   $\alpha = \frac{1}{A_c} \int_{A_c} \left( \frac{V}{V_{avg}} \right)^3 dA_c$   $\alpha = 2.0$  fully developed laminar pipe flow  $\alpha \approx 1.05$  fully developed turbulent pipe flow **Bernoulli equation**:  $\frac{P_1}{\rho g} + \frac{V_1^2}{2g} + z_1 = \frac{P_2}{\rho g} + \frac{V_2^2}{2g} + z_2$  along a streamline from 1 to 2. **Momentum equation for a CV**:  $\sum \vec{F} = \sum \vec{F}_{\text{gravity}} + \sum \vec{F}_{\text{pressure}} + \sum \vec{F}_{\text{viscous}} + \sum \vec{F}_{\text{other}} = \frac{d}{dt} \int_{CV} \rho \vec{V} dV + \sum_{\text{out}} \beta \dot{m} \vec{V} - \sum_{\text{in}} \beta \dot{m} \vec{V}$ • Head form of energy equation:  $\frac{P_1}{\rho_1 g} + \alpha_1 \frac{V_1^2}{2g} + z_1 + h_{\text{pump}, u} = \frac{P_2}{\rho_2 g} + \alpha_2 \frac{V_2^2}{2g} + z_2 + h_{\text{turbine}, e} + h_L$ , where 1 = inlet, 2 = outlet, and the useful pump head and extracted turbine head are  $h_{\text{pump}, u} = \frac{\eta_{\text{pump}} \dot{W}_{\text{pump shaft}}}{\dot{m}g}$  and  $h_{\text{turbine}, e} = \frac{\dot{W}_{\text{turbine shaft}}}{\eta_{\text{turbine}, m} \dot{m}g}$ Turbomachinery: Net head =  $H = h_{pump,u} = \left(\frac{P}{\rho g} + \frac{V^2}{2g} + z\right) - \left(\frac{P}{\rho g} + \frac{V^2}{2g} + z\right)$ • Water horsepower =  $\dot{W}_{\text{pump},u} = \dot{m}gH = \rho \dot{V}gH$ , Brake horsepower =  $\dot{W}_{\text{shaft}} = bhp$ To match a pump (available head) to a piping system (required head), match  $H_{\text{available}} = H_{\text{required}}$ Pump and turbine performance parameters:  $C_{\varrho} = \text{Capacity coefficient} = \frac{\dot{V}}{\omega D^{3}} \qquad C_{H} = \text{Head coefficient} = \frac{gH}{\omega^{2}D^{2}} \qquad C_{P} = \text{Power coefficient} = \frac{bhp}{\rho\omega^{3}D}$  $\eta_{\text{pump}} = \frac{\dot{W}_{\text{pump,u}}}{bhp} = \frac{\rho\dot{V}gH}{bhp} = \frac{C_{\varrho}C_{H}}{C_{P}} = \text{function of } C_{\varrho} \qquad \eta_{\text{turbine}} = \frac{bhp}{\dot{W}_{\text{turbine,e}}} = \frac{bhp}{\rho\dot{V}gH} = \frac{C_{P}}{C_{\varrho}C_{H}} = \text{function}$  $\rho \omega^3 D^5$  $\frac{C_P}{C_Q C_H} = \text{ function of } C_P$  $\frac{H_{\rm B}}{H_{\rm A}} =$  $\frac{bhp_{\rm B}}{dm_{\rm B}} = \frac{\rho_{\rm B}}{\omega_{\rm B}}$ **Pump and turbine affinity laws:**  $\left| \frac{\dot{V}_{B}}{\dot{V}_{A}} \right| = \frac{\omega_{B}}{\omega_{A}} \left( \frac{D_{B}}{D_{A}} \right)^{2}$  $\left(\frac{\omega_{\rm B}}{\omega_{\rm A}}\right)$  $\left(\frac{D_{\rm B}}{D_{\rm A}}\right)$  $\frac{D_{\rm B}}{D_{\rm A}}$ 

bhp<sub>A</sub>

•	Grade lines: <i>Energy Grade Line</i> = $\frac{P}{\rho g} + \frac{V^2}{2g} + z$ , <i>Hydraulic Grade Line</i> = $\frac{HGL}{P} = \frac{P}{\rho g} + z$
•	Pipe flows: $Re = \frac{\rho VD}{\mu} = \frac{VD}{V} \left[ h_{L, \text{ total}} = \sum h_{L, \text{ major}} + \sum h_{L, \text{ minor}} \right], Major head loss = \left[ h_{L} = f \frac{L}{D} \frac{V^{2}}{2g} \right] f = \frac{8\tau_{w}}{\rho V^{2}} = \text{fnc} \left( \text{Re}, \frac{\varepsilon}{D} \right),$
	$\vec{m} = \rho VA$ , Minor head loss = $h_L = K_L \frac{V^2}{2g}$ , Fully developed laminar pipe flow, $\alpha = 2$ $f = 64/\text{Re}$ . Near wall, $\tau_{\text{wall}} = \mu \frac{du}{dy}_{\text{wall}}$
	<i>Fully developed turbulent</i> pipe flow, $\alpha \cong 1.05$ $\frac{1}{\sqrt{f}} \approx -2.0 \log_{10} \left( \frac{\varepsilon/D}{3.7} + \frac{2.51}{\text{Re}\sqrt{f}} \right)$ (Colebrook eq., Moody chart)
•	Hydraulic diameter: $D_h = \frac{4A_c}{p}$ , where $A_c$ is the cross-sectional area and p is the <i>wetted</i> perimeter
•	<b>Continuity equation:</b> $\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot (\rho \vec{V}) = 0$ . If incompressible, $\vec{\nabla} \cdot \vec{V} = 0$
	In <i>Cartesian</i> coordinates, $\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$ , and in <i>cylindrical</i> coordinates, $\frac{1}{r} \frac{\partial (ru_r)}{\partial r} + \frac{1}{r} \frac{\partial u_{\theta}}{\partial \theta} + \frac{\partial u_z}{\partial z} = 0$
•	<b>Stream function</b> : Cartesian (x-y plane): $u = \frac{\partial \psi}{\partial y}$ $v = -\frac{\partial \psi}{\partial x}$ ; Cylindrical planar (r- $\theta$ plane): $u_r = \frac{1}{r} \frac{\partial \psi}{\partial \theta}$ $u_{\theta} = -\frac{\partial \psi}{\partial r}$
•	<b>Navier-Stokes equation</b> : (for incompressible, Newtonian flow) $\rho \frac{D\vec{V}}{Dt} = \rho \left[ \frac{\partial \vec{V}}{\partial t} + (\vec{V} \cdot \vec{\nabla}) \vec{V} \right] = -\vec{\nabla}P + \rho \vec{g} + \mu \nabla^2 \vec{V}$
•	<b>Creeping flow</b> : For Re << 1, $\vec{\nabla} P \approx \mu \nabla^2 \vec{V}$ .
•	<b>Potential flow (Irrotational flow)</b> : Since $\nabla \times \vec{V} = 0$ , then $\vec{V} = \nabla \phi$ , where $\phi$ is the velocity potential function. $\nabla^2 \phi = 0$
	Cartesian coordinates: $\nabla^2 \phi = \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2} = 0$ . Cylindrical coordinates: $\nabla^2 \phi = \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial \phi}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2} + \frac{\partial^2 \phi}{\partial z^2} = 0$
	If flow is also 2-D, then $\nabla^2 \psi = 0$ as well. Superposition of both $\phi$ and $\psi$ is valid for potential flow.
•	<b>Boundary layers</b> : $\operatorname{Re}_{x} = \frac{\rho U x}{\mu} = \frac{U x}{v}$ , where x is <i>along</i> the body. $U(x)$ is the outer flow (just outside the boundary layer).
	For steady flow, continuity: $\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$ ; x-momentum: $u\frac{\partial u}{\partial x} + v\frac{\partial u}{\partial y} = U\frac{dU}{dx} + v\frac{\partial^2 u}{\partial y^2}$ ; y-momentum: $\frac{\partial P}{\partial y} \approx 0$
٠	Flat plate boundary layer:
	If laminar, $(\operatorname{Re}_x < 5 \times 10^5)$ , $\frac{\partial}{x} = \frac{4.91}{\sqrt{\operatorname{Re}_x}} \left  \frac{\partial^*}{x} = \frac{1.72}{\sqrt{\operatorname{Re}_x}} \right  C_{f,x} = \frac{2\tau_w}{\rho U^2} = \frac{0.664}{\sqrt{\operatorname{Re}_x}} \left  C_f = C_D = \frac{1.33}{\sqrt{\operatorname{Re}_x}} \right $
	If <i>laminar</i> , $(\operatorname{Re}_{x} < 5 \times 10^{5})$ , $\frac{\delta}{x} = \frac{4.91}{\sqrt{\operatorname{Re}_{x}}}$ $\frac{\delta^{*}}{x} = \frac{1.72}{\sqrt{\operatorname{Re}_{x}}}$ $C_{f,x} = \frac{2\tau_{w}}{\rho U^{2}} = \frac{0.664}{\sqrt{\operatorname{Re}_{x}}}$ $C_{f} = C_{D} = \frac{1.33}{\sqrt{\operatorname{Re}_{x}}}$ If <i>turbulent</i> and <i>smooth</i> , $(5 \times 10^{5} < \operatorname{Re}_{x} < 10^{7})$ , $\frac{\delta}{x} \approx \frac{0.38}{(\operatorname{Re}_{x})^{1/5}}$ $\frac{\delta^{*}}{x} \approx \frac{0.048}{(\operatorname{Re}_{x})^{1/5}}$ $C_{f,x} \approx \frac{0.059}{(\operatorname{Re}_{x})^{1/5}}$ $C_{f} = C_{D} = \frac{0.074}{\operatorname{Re}_{x}^{1/5}}$
•	<b>Drag and Lift on bodies</b> : $C_D = \frac{F_D}{\frac{1}{2}\rho V^2 A} C_L = \frac{F_L}{\frac{1}{2}\rho V^2 A}$ , where $A$ = projected frontal area <i>or</i> planform area. $C_D$ includes skin friction
	and pressure drag. For bodies without ground effect, required power = $\frac{\dot{W} = F_D V}{V}$ . For vehicles in ground effect, the required <b>power</b>
	to the wheels = $\dot{W} = \mu_{\text{rolling}}WV + \frac{1}{2}\rho V^3 C_D A$ , where $\mu_{\text{rolling}} = \text{coefficient of rolling resistance, and } W$ is the vehicle weight.
•	Isentropic compressible flow for air $(k = 1.4)$ : $\frac{T_0}{T} = 1 + 0.2 \text{Ma}^2 \frac{\rho_0}{\rho} = (1 + 0.2 \text{Ma}^2)^{2.5} \frac{P_0}{P} = (1 + 0.2 \text{Ma}^2)^{3.5} \frac{\dot{m}_{\text{max}}}{\sqrt{RT_0}} = \frac{0.6847 P_0 A^*}{\sqrt{RT_0}}$
•	Normal shock equations for air $(k = 1.4)$ : $\frac{T_2}{T_1} = (2 + 0.4 \text{Ma}_1^2) \frac{2.8 \text{Ma}_1^2 - 0.4}{5.76 \text{Ma}_1^2} \left[ \frac{P_2}{P_1} = \frac{(2.8 \text{Ma}_1^2 - 0.4)}{2.4} \right] \frac{\rho_2}{\rho_1} = \frac{2.4 \text{Ma}_1^2}{(2 + 0.4 \text{Ma}_1^2)}$

• Moody Chart:

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Reynolds number, Re